



# 6-AXIS GENERAL PURPOSE ROBOT

## **ACT-F210R2700**

Top class heavy duty. Powerful, fast and accurate. Suitable for pick-n-place, machine tending, palletizing, polishing, glue dispensing and painting.

### **Robot specifications**

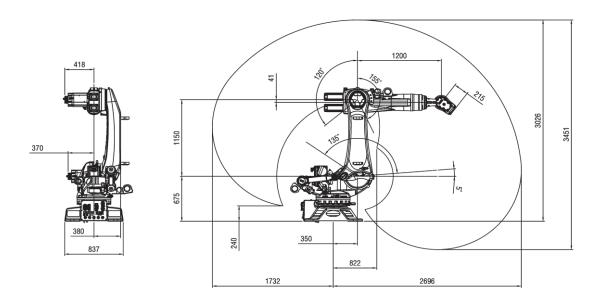
Basic data		
Model No.	ACT-F210R2700	
Number of axes	6	
Maximum payload	210 kg	
Maximum stroke	2700mm	
IP class	J1, J2 - IP56; J3, J4, J5, J6- IP67	
Mounting position	Floor type	
Approx. weight	1130 kg (without cabinet)	
Repeatability	±0.06 mm	
Internal air duct	Ф10	
Motion range		
J1 axis S	±185°	
J2 axis L	+85°~-50°	
J3 axis U	+210°~-65°	
J4 axis R	±350°	
J5 axis B	±125°	
J6 axis T	±350°	
Speed with rated payload		
J1 axis S	123°/s	
J2 axis L	115°/s	
J3 axis U	112°/s	
J4 axis R	179°/s	
J5 axis B	172°/s	
J6 axis T	219°/s	

Electrical cabinet specifications		
Dimensions	560*500*800mm	
Approx. weight	100KG	
Cooling method	Natural cooling	
Input power	380VAC 50/60Hz	
Grounding	Industrial grounding (grounding resistance below $100\Omega$ )	
I/O terminals	·16 digital inputs	
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	·2 analog outputs (optional)	
Position control mode	EtherCAT, TCP/IP	
Serial port I/F	RS485*1, RS422*1, RS232*1, CAN*1, USB*1	
RAM capacity	JOB 200,000 steps, 10,000 robot commands (200MB)	
Driving unit	6-axis AC servo system. External axis can be added as an option.	

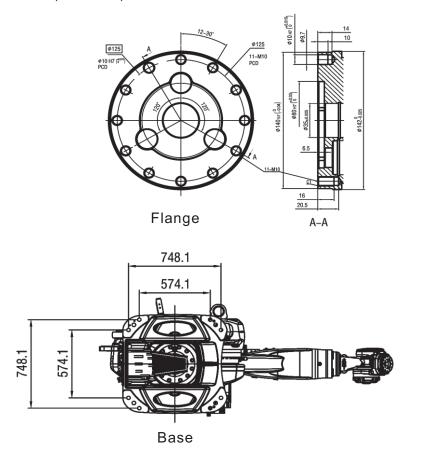
Operating conditions		
Use temperature	0~45°C	
Storage temperature	-20~60°C	
Humidity	10~90% RH, no condensing	
Vibrations	Below 0.5G	
Altitude	Below 1000m. (Degrade if over 1000m, max 2000m)	
Other requirements	·With no corrosive or combustible gas	
	·With no water, oil or drug splashing	
	·With no electromagnetic field nearby	
	·With no radiations nearby	



### Working envelope (unit: mm)



### Flange and base dimensions (unit: mm)



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