



4-AXIS HANDLING ROBOT

ACT10B-1400

Fast, accurate and reliable.
Suitable for pick-n-place and palletizing.

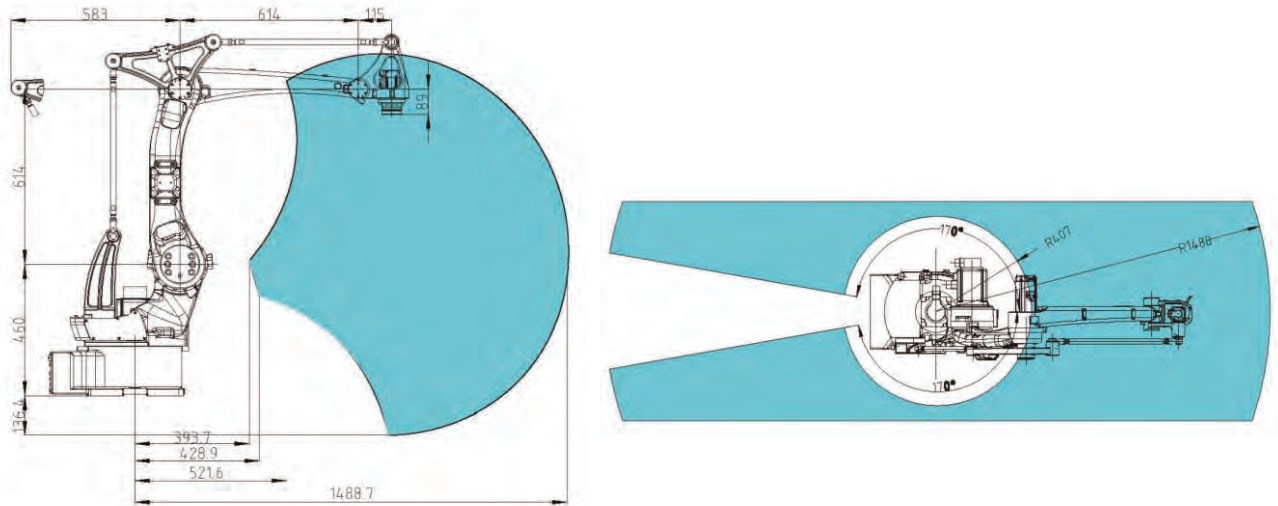
Robot specifications

Basic data	
Model No.	ACT10B-1400
Number of axes	4
Maximum payload	12 kg
Maximum stroke	1400mm
IP class	J1, J2 - IP56; J3, J4- IP67
Mounting position	Floor type
Approx. weight	165 kg (without cabinet)
Repeatability	±0.08 mm
Internal air duct	Φ10
Motion range	
J1 axis S	±170°
J2 axis L	+80°~-32°
J3 axis U	+20°~-90°
J4 axis R	±360°
Speed with rated payload	
J1 axis S	223°/s
J2 axis L	173°/s
J3 axis U	300°/s
J4 axis R	481°/s

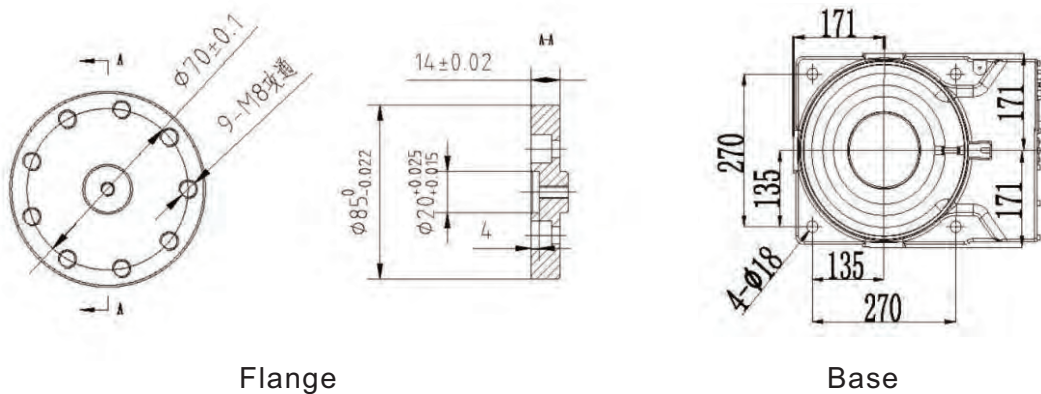
Electrical cabinet specifications	
Dimensions	490*400*365mm
Approx. weight	40KG
Cooling method	Natural cooling
Input power	220VAC 50/60Hz
Grounding	Industrial grounding (grounding resistance below 100Ω)
I/O terminals	·16 digital inputs ·16 digital outputs
Position control mode	EtherCAT, TCP/IP
Serial port I/F	RS485*1, RS422*1, RS232*1, CAN*1, USB*1
RAM capacity	JOB 200,000 steps, 10,000 robot commands (200MB)
Driving unit	6-axis AC servo system. External axis can be added as an option.

Operating conditions	
Use temperature	0~45°C
Storage temperature	-20~60°C
Humidity	10~90% RH, no condensing
Vibrations	Below 0.5G
Altitude	Below 1000m. (Degrade if over 1000m, max 2000m)
Other requirements	·With no corrosive or combustible gas ·With no water, oil or drug splashing ·With no electromagnetic field nearby ·With no radiations nearby

► Working envelope (unit: mm)



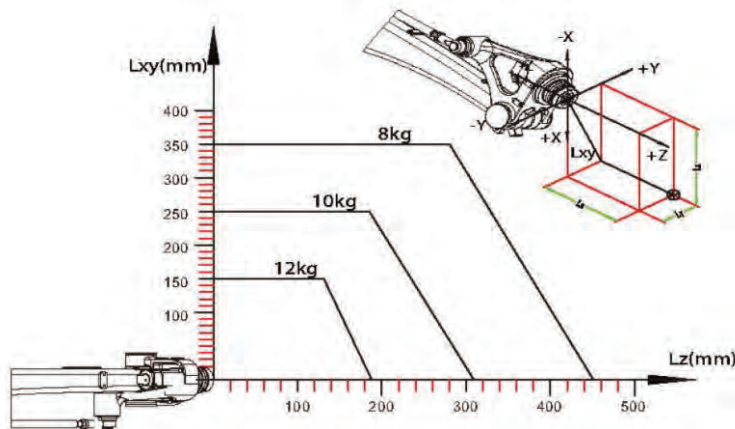
► Flange and base dimensions (unit: mm)



Flange

Base

► Payload diagram



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