



6-AXIS GENERAL PURPOSE ROBOT

ACT30-1700

Enclosed design. Heavy duty.

Suitable for pick-n-place, machine tending, palletizing, polishing painting, etc.

Robot specifications

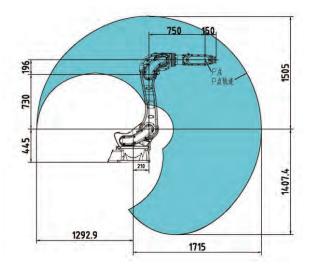
Basic data		
Model No.	ACT30-1700	
Number of axes	6	
Maximum payload	30 kg	
Maximum stroke	1700mm	
IP class	J1, J2 - IP56; J3, J4, J5, J6- IP67	
Mounting position	Floor type, wall type, ceiling type	
Approx. weight	283 kg (without cabinet)	
Repeatability	±0.08 mm	
Internal air duct	Ф10	
Motion range		
J1 axis S	±165°	
J2 axis L	+80°~-150°	
J3 axis U	+130°~-60°	
J4 axis R	±190°	
J5 axis B	+20°~-200°	
J6 axis T	±360°	
Speed with rated payload		
J1 axis S	130°/s	
J2 axis L	130 °/s	
J3 axis U	144°/s	
J4 axis R	224 °/s	
J5 axis B	333 °/s	
J6 axis T	374 °/s	

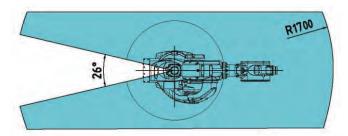
Electrical cabinet specifications	
Dimensions	650*495*580mm
Approx. weight	80KG
Cooling method	Natural cooling
Input power	380VAC 50/60Hz
Grounding	Industrial grounding (grounding resistance below 100Ω)
	·16 digital inputs
I/O terminals	·16 digital outputs
	·2 analog outputs (optional)
Position control mode	EtherCAT, TCP/IP
Serial port I/F	RS485*1, RS422*1, RS232*1, CAN*1, USB*1
RAM capacity	JOB 200,000 steps, 10,000 robot commands (200MB)
Driving unit	6-axis AC servo system. External axis can be added as an option.

Operating conditions	
Use temperature	0~45°C
Storage temperature	-20~60°C
Humidity	10~90% RH, no condensing
Vibrations	Below 0.5G
Altitude	Below 1000m. (Degrade if over 1000m, max 2000m)
Other requirements	·With no corrosive or combustible gas
	·With no water, oil or drug splashing
	·With no electromagnetic field nearby
	·With no radiations nearby

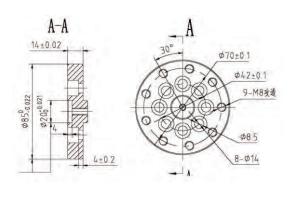


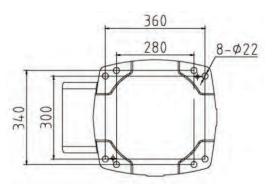
▶ Working envelope (unit: mm)





Flange and base dimensions (unit: mm)

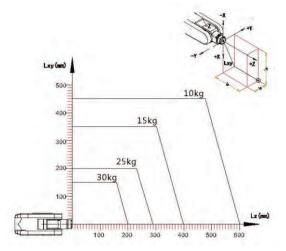




Flange

Base

▶ Payload diagram



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